

CEGM1000

Modelling, Uncertainty and Data for Engineers

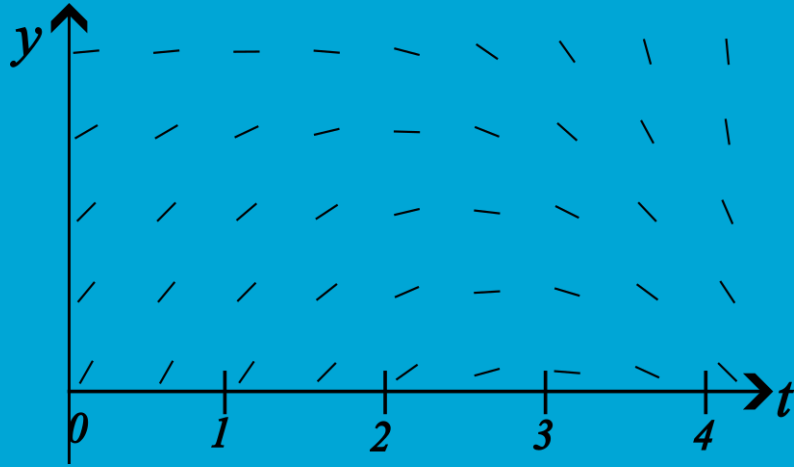
Week 1.6

Numerical modelling (Beyond Fundamentals)

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with A LOT of support from Isabel Slingerland and the
rest of MUDEs' wonderful team





Learning objectives

At the end of this lecture, you should be able to

- Discuss the characteristics of Explicit and Implicit Numerical schemes
- Schematize numerical solutions of ODEs and PDEs
- Solve initial and boundary value problems numerically
- Solve partial differential equations

Contents

- Explicit and Implicit numerical schemes: single step
 - Initial Value Problems
- Multiple step and multi stage schemes
 - Initial Value Problems
- Second degree ODEs
 - Boundary Value Problems
- Solving PDEs: an introduction

Differential equations –ODEs, PDEs

Ice growth

First order ODE →

$$\rho_{ice} \frac{dh_{ice}}{dt} = -k_{ice} \frac{T_{water} - T_{air}}{h_{ice}}$$

Beam deformation

Second order ODE →

$$\frac{d^2 v}{dz^2} = \frac{-1}{EI} \left(-\frac{qz^2}{2} + qLz - \frac{qL^2}{2} \right)$$

Diffusion equation 1D

Second order PDE →

$$\frac{du}{dt} = k \frac{d^2 u}{dx^2}$$

How many constraints do the following equations need?



A. 1 and 1

B. 1 and 2

C. 2 and 1

D. 1 and 3

E. 3 and 1

F. 2 and 2

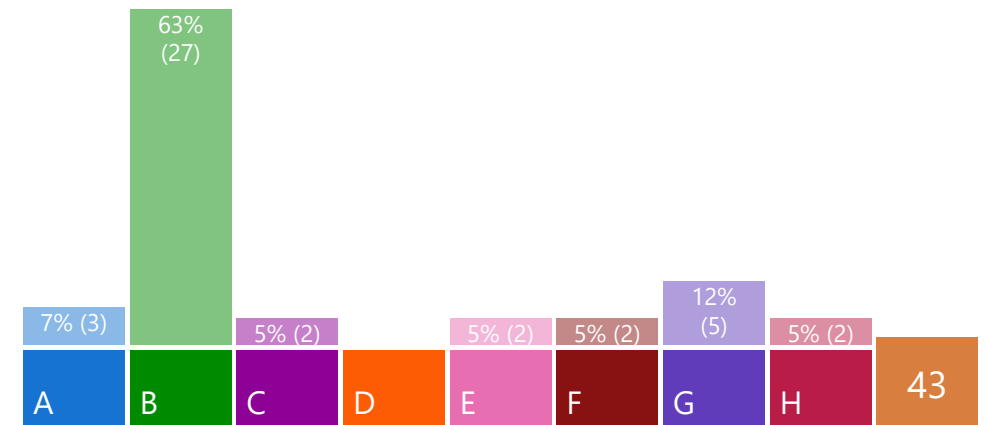
G. 2 and 3

H. 3 and 2

$$\rho_{ice} \frac{dh_{ice}}{dt} = -k_{ice} \frac{T_{water} - T_{air}}{h_{ice}}$$

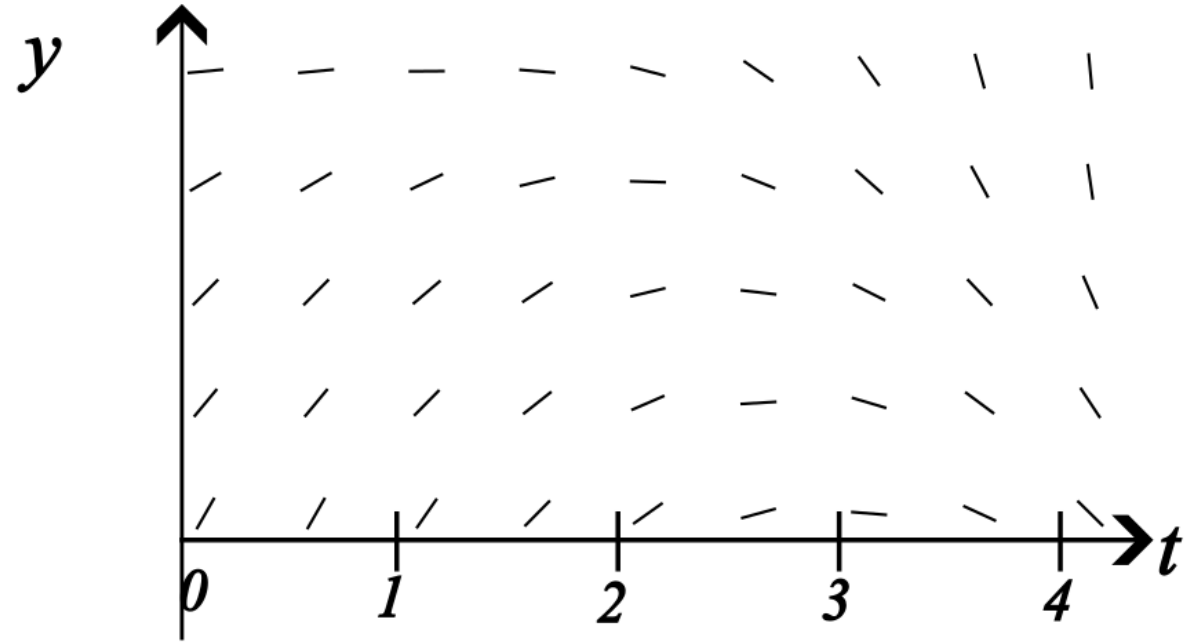
and

$$\frac{d^2v}{dz^2} = \frac{-1}{EI} \left(-\frac{qz^2}{2} + qLz - \frac{qL^2}{2} \right)$$



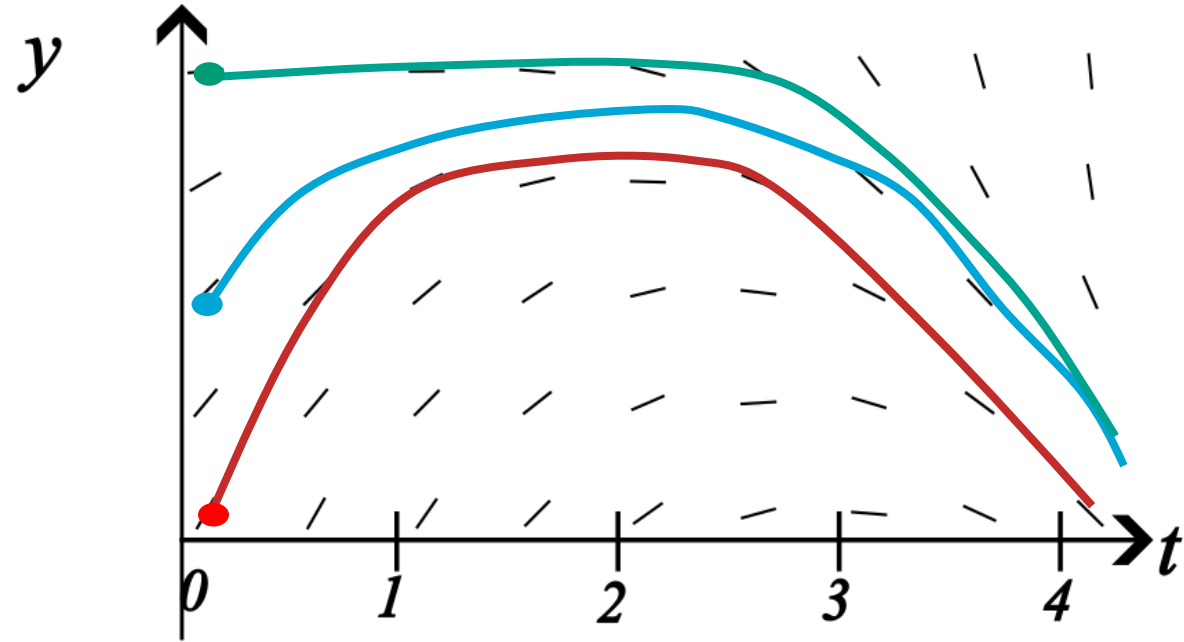
Initial Value Problem

$$\frac{dy}{dt} = -y + e^t \quad \rightarrow$$



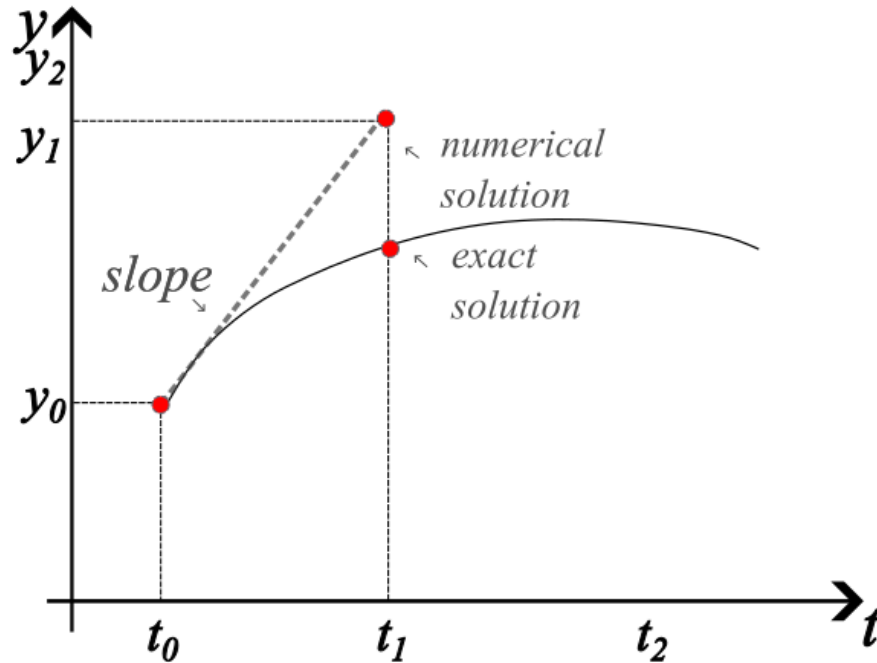
Initial Value Problem

$$\frac{dy}{dt} = -y + e^t \quad \rightarrow$$



Any ODE, no matter the order, that has a time dependency has a solution
Completely dependent on the initial value!

Explicit Euler



$$t_{i+1} = t_i + \Delta t$$

$$y_{i+1} = y_i + \Delta t * slope_i$$

$$y_1 = y_0 + \Delta t * slope_0$$

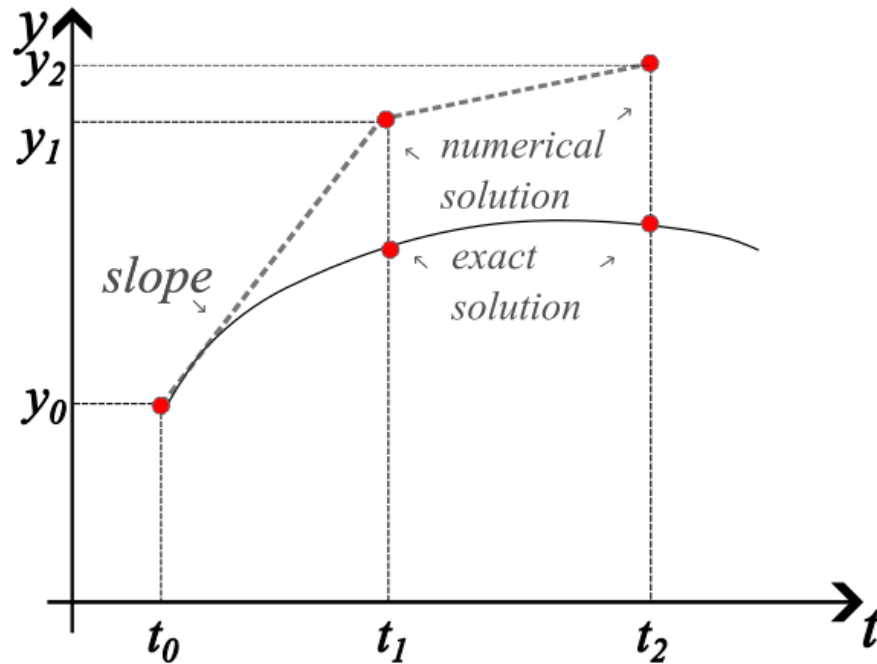
The slope is computed using the Forward Difference formula, first-order accurate.

$$\text{Truncation error} = y_1^{TSE} - y_1^{FE}$$

$$= y_0 + \Delta t y'_0 + \frac{\Delta t^2}{2!} y''_0 + \dots - (y_0 + \Delta t y'_0)$$

$$= \frac{\Delta t^2}{2!} y''_0 + \dots \approx O(\Delta t^2)$$

Explicit Euler



$$t_{i+1} = t_i + \Delta t$$

$$y_{i+1} = y_i + \Delta t * slope_i$$

$$y_2 = y_1 + \Delta t * slope_1$$

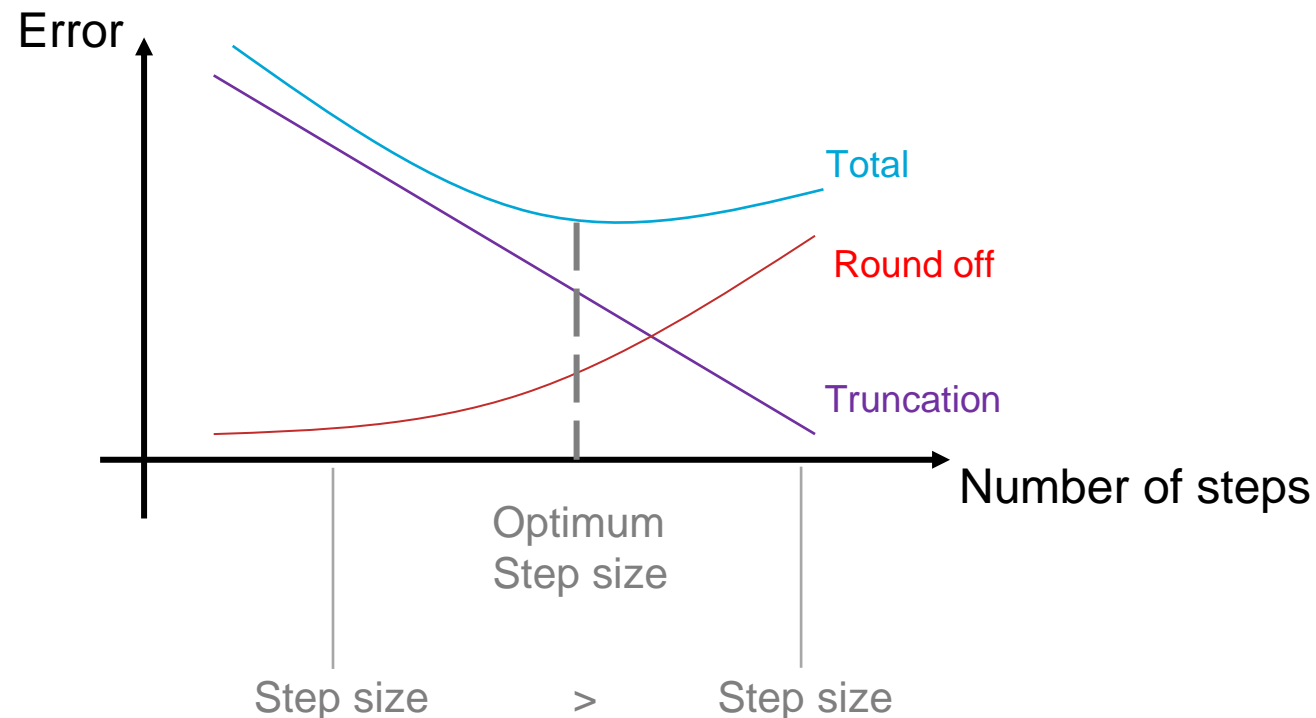
$$\text{Total truncation error} = \sum_{i=0}^{n-1} y_{i+1}^{TSE} - y_{i+1}^{FE}$$

$$= \sum_{i=0}^{n-1} \frac{\Delta t^2}{2!} y''_i + \dots \approx \frac{\Delta t^2}{2!} \frac{b-a}{\Delta t} y''_i$$

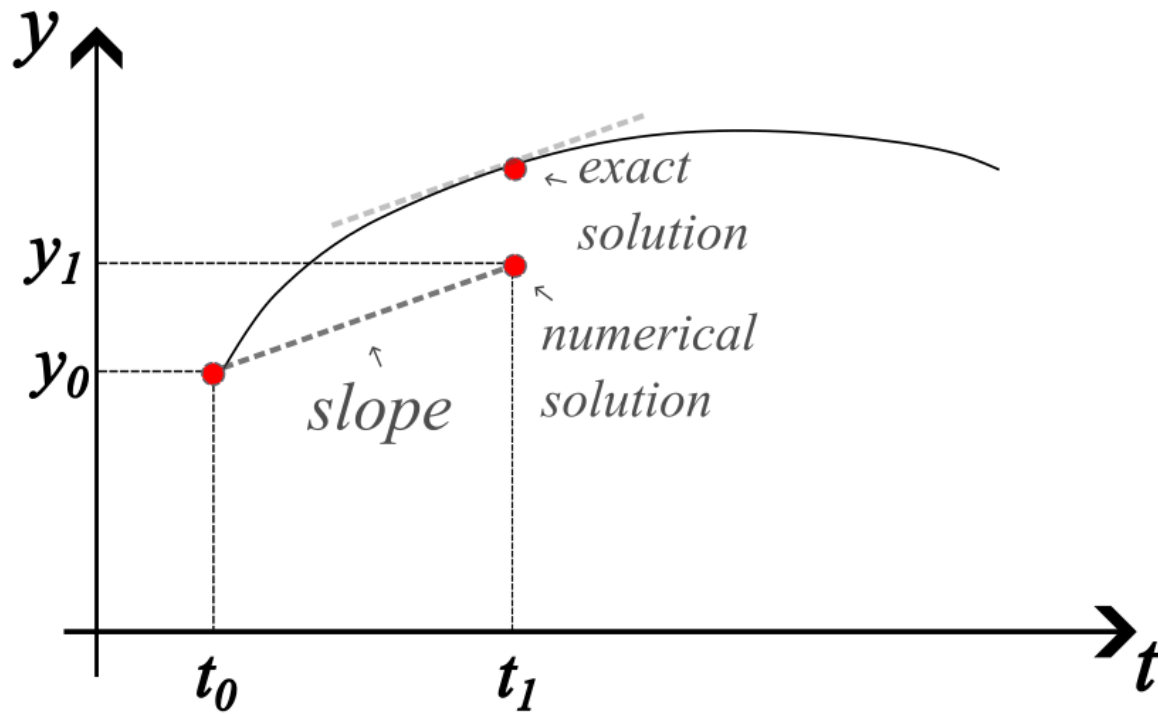
$$\approx \frac{\Delta t}{2!} (b-a) \overline{y''} \approx O(\Delta t)$$

Round-off error & the better compromise

Error using 16 bits of memory = -1.220703125
Error using 32 bits of memory = -0.00022351741790771484
Error using 64 bits of memory = 2.7755575615628914e-13



Implicit Euler



$$t_{i+1} = t_i + \Delta t$$

$$y_{i+1} = y_i + \Delta t * slope_{i+1}$$

$$y_1 = y_0 + \Delta t * slope_1$$

The slope is computed using the Backward Difference formula, first-order accurate.

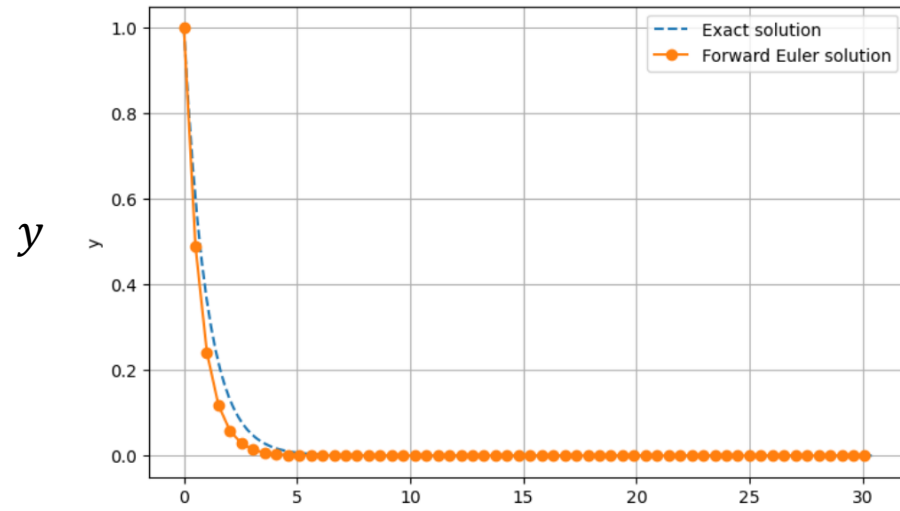
Total truncation error $\approx O(\Delta t)$

Stability

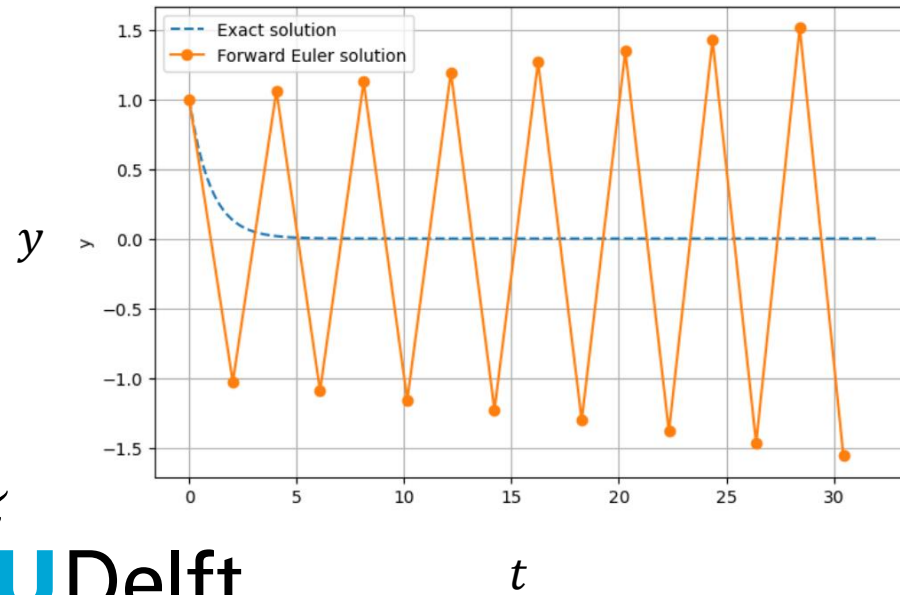
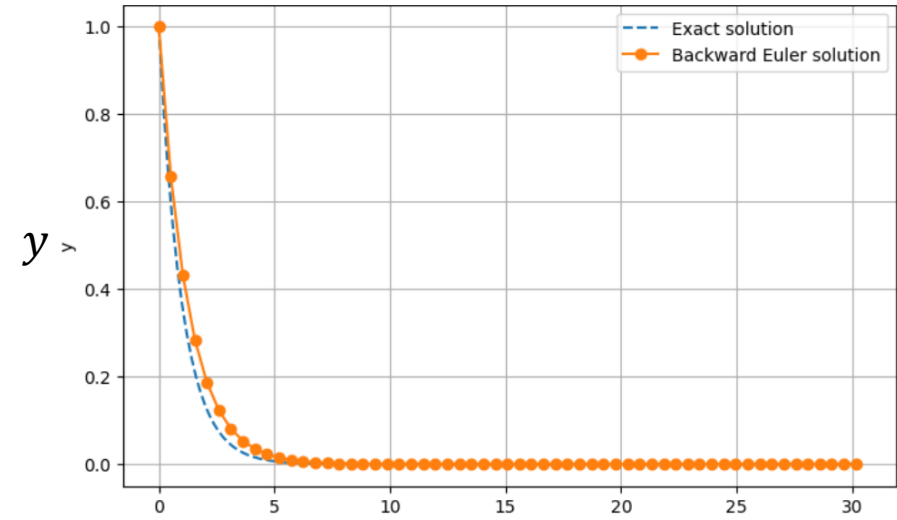
Explicit

$$\frac{dy}{dt} = -\alpha y$$

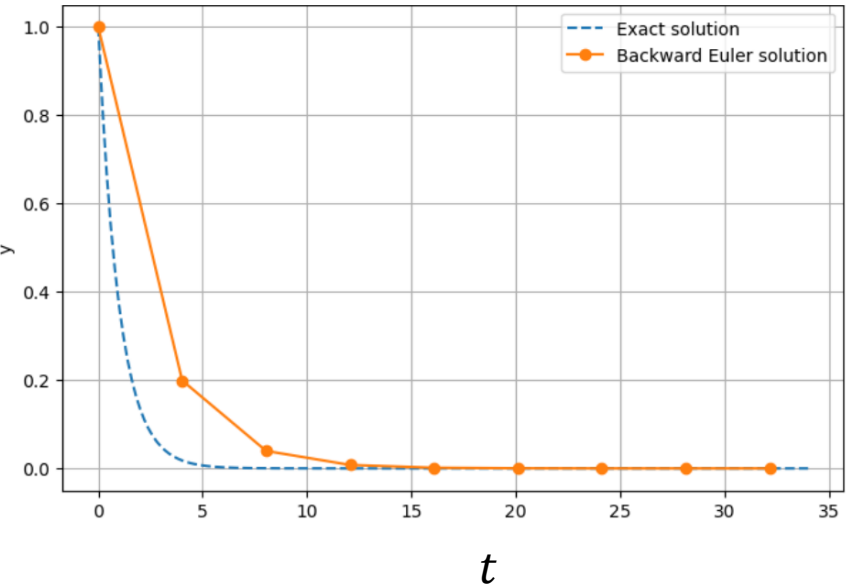
Implicit



← Small Step →



← Large Step →



Non-linear ODE

$$\frac{dp(t)}{dt} = -p^{3/2} + 5 \cdot p_{cst}(1 - e^{-t})$$

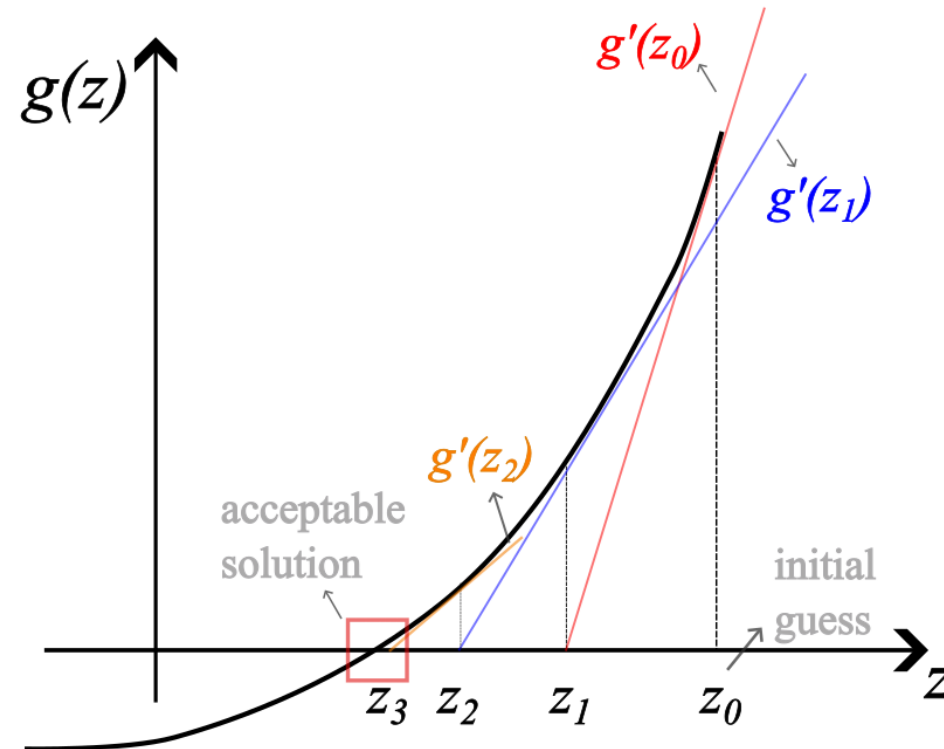
$$p_{i+1} = p_i + \Delta t \left(-p_i^{3/2} + 5p_{cst} \cdot (1 - e^{-t_i}) \right)$$

Solved directly

$$p_{i+1} = p_i + \Delta t \left(-p_{i+1}^{3/2} + 5p_{cst} * (1 - e^{-t_{i+1}}) \right)$$

Solved iteratively

Non-linear ODE: Newton-Rhapson (iterative) method



How do you increase the accuracy without compromising computational time?

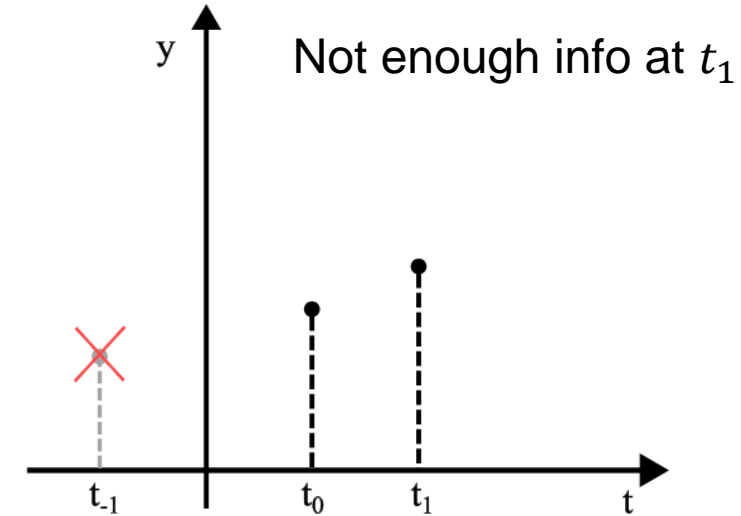
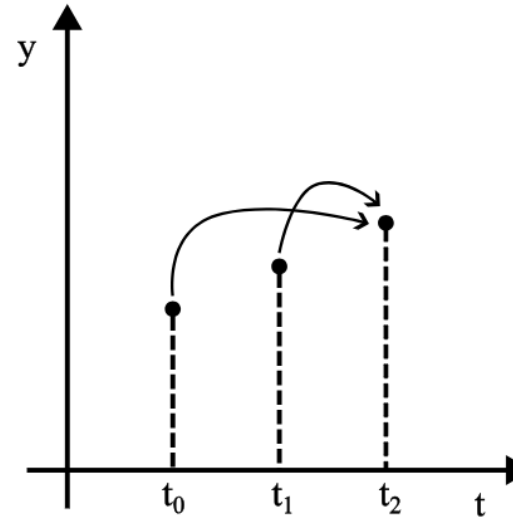


Multi-step methods

- Adams-Bashfort are explicit methods of higher accuracy
- AB are not self starting!
- Adams-Moulton are implicit methods of higher accuracy
- AM are self starting but require iteration

Adams-Bashfort
second order accurate

$$y_{i+1} = y_i + \frac{\Delta t}{2} (3y'_i - y'_{i-1})$$



Multi-stage methods

The main error of simple single step methods is assuming that the slope does not change between i and $i + 1$

- Modified Euler

$$y_{i+1} = y_i + \Delta t (y'_i + y'_{i+1*})/2$$

- Midpoint

$$y_{i+1} = y_i + \Delta t y'_{i+\frac{1}{2}*}$$

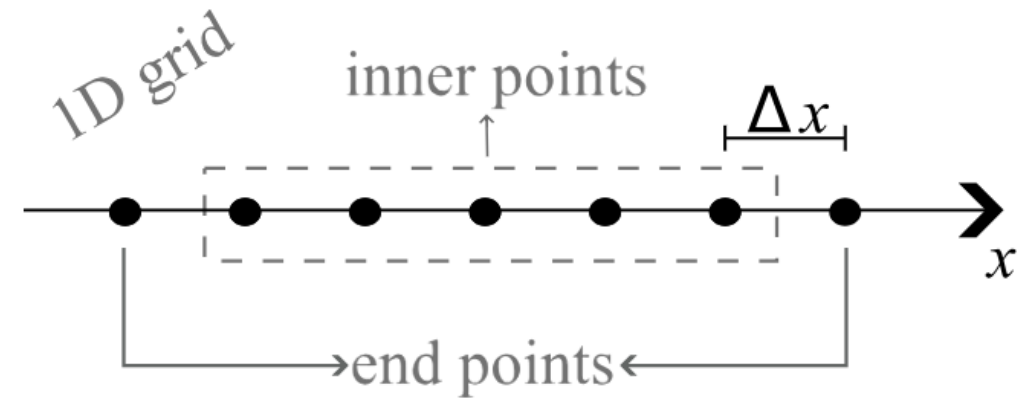
- Runge-Kutta

$$y_{i+1} = y_i + \Delta t (K_1 + K_2)$$

Second degree ODE

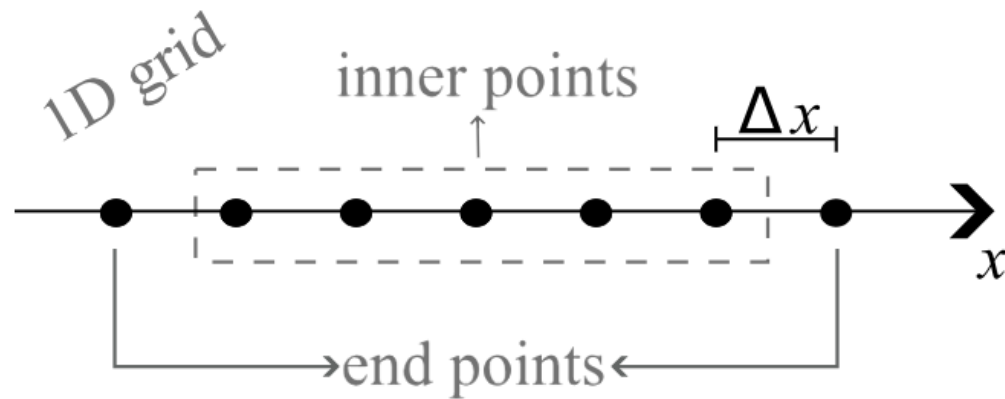
$$\frac{d^2 y}{dt^2} = \frac{dy}{dt} - y + \cos t = 0 \quad \rightarrow \text{IVP}$$

$$\frac{d^2 T}{dx^2} - \alpha_1 (T - T_s) = 0 \quad \rightarrow \text{BVP}$$



Second degree ODE: Boundary Conditions

$$\frac{d^2 T}{dx^2} - \alpha_1 (T - T_s) = 0$$



$$\frac{d^2 y}{dx^2} = g\left(x, y, \frac{dy}{dx}\right)$$

- Dirichlet

$$y(x = a) = Y_a \text{ and } y(x = b) = Y_b$$

- Neumann

$$\left. \frac{dy}{dx} \right|_{x=a} = D_a \text{ and } \left. \frac{dy}{dx} \right|_{x=b} = D_b$$

- Mixed

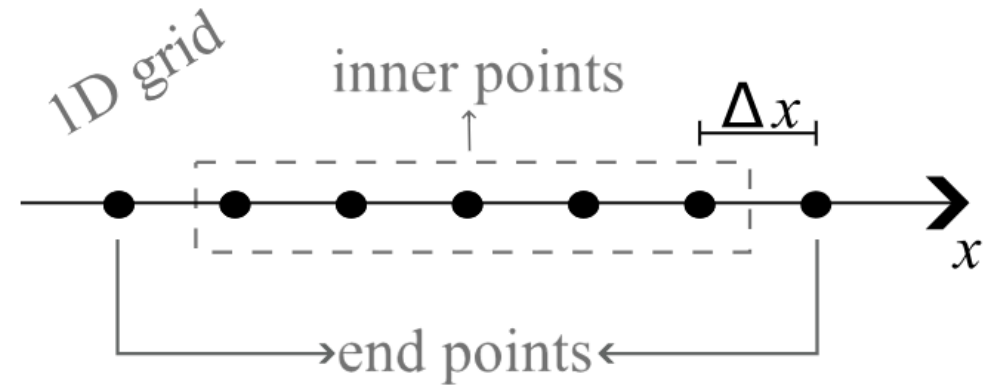
Central Difference: $f'' = \frac{f(x_i - \Delta x) - 2f(x_i) + f(x_i + \Delta x))}{\Delta x^2}$

Exercise

$$\frac{d^2T}{dx^2} - \alpha(T - T_s) = 0, \quad x \in (0, 0.1)$$

Use 5 points for your grid

$$T(0) = 473[K], \quad T(0.1) = 293[K]$$



Partial Differential Equations

- 1.- Discretization of the space derivative
- 2.- Discretization of the time derivative
- 3.- Parameter definition
- 4.- Grid creation
- 5.- Define initial conditions
- 6.- Define Boundary Conditions
- 7.- Build your system of equations
- 8.- Solve the system
- 9.- Update values and increment one time step

$$\frac{\partial^2 \phi}{\partial x^2} + \frac{\partial^2 \phi}{\partial y^2} = 2xy \text{ Poisson's equation}$$

$$\frac{du}{dt} = \nu \frac{d^2 u}{dx^2} \text{ diffusion equation}$$

$$\frac{dc}{dt} + v \frac{dc}{dx} = 0 \text{ convection equation}$$

Exercise: discretize the convection equation using a central difference for space (2nd order accurate) and a forward difference for time (1st order accurate)

$$\frac{dc}{dt} + v \frac{dc}{dx} = 0 \quad \text{convection equation}$$

How many constraints are needed?

- A. 1
- B. 2
- C. 3
- D. 4

